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this book is a collection of papers presented at the international workshop on new approaches for multidimensional signal processing namsp 2020 held at technical university of sofia sofia bulgaria during 09 11 july 2020 the book covers research papers in the field of n dimensional multicomponent image processing multidimensional image representation and super resolution 3d image processing and

reconstruction md computer vision systems multidimensional multimedia systems neural networks for md image processing data based md image retrieval and knowledge data mining watermarking hiding and encryption of md images md image processing in robot systems tensor based data processing 3d and multi view visualization forensic analysis systems for md images and many more

ebook introductory chemistry an atoms first approach

this book presents the recent research advances in linear and nonlinear control techniques from both a theoretical and practical standpoint motion planning and related control challenges are key parts of robotics indeed the literature on the planning of geometric paths and the generation of time based trajectories while accounting for the compatibility of such paths and trajectories with the kinematic and dynamic constraints of a manipulator or a mobile vehicle is extensive and rich in historical references path planning is vital and critical for many different types of robotics including autonomous vehicles multiple robots and robot arms in the case of multiple robot route planning it is critical to produce a safe path that avoids colliding with objects or other robots when designing a safe path for an aerial or underwater robot the 3d environment must be considered as the number of degrees of freedom on a robot arm increases so does the difficulty of path planning as a result safe pathways for high dimensional systems must be developed in a timely manner nonetheless modern robotic applications particularly those requiring one or more robots to operate in a dynamic environment e g human robot collaboration and physical interaction surveillance or exploration of unknown spaces with mobile agents etc pose new and exciting challenges to researchers and practitioners for instance planning a robot s motion in a dynamic environment necessitates the real time and online execution of difficult computational operations the development of efficient solutions for such real time computations which could be offered by specially designed computational architectures optimized algorithms and other unique contributions is thus a critical step in the advancement of present and future oriented robotics

this book constitutes the proceedings of the 16th international conference on parallel computing technologies pact 2021 which was held during september 13 18 2021 the conference was planned to take place in kaliningrad russia but changed to an online event due to the covid 19 pandemic the 24 full and 12 short papers included in this book were carefully reviewed and selected from 62 submissions they were organized in topical sections as follows parallel programming methods and tools applications memory efficient data structures experimental studies job management essential algorithms computing services and cellular automata

the second of two volumes in the electronic design automation for integrated circuits handbook second edition electronic design automation for ic implementation circuit design and process technology thoroughly examines real time logic rtl to gdsii a file format

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